# SMART MACHINES



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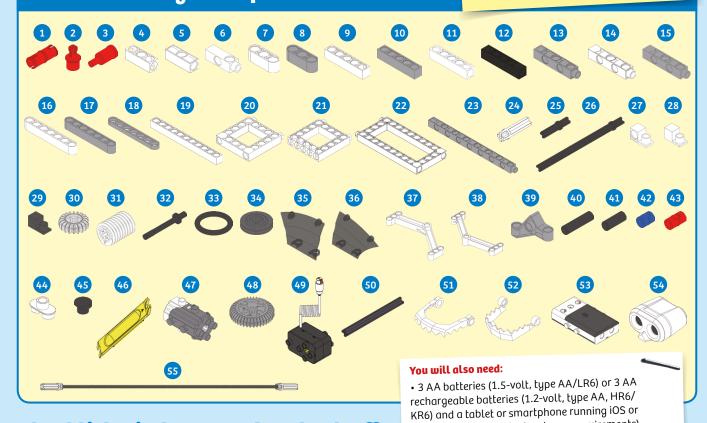




**GOOD TO KNOW!** If you are missing any parts, please contact Thames & Kosmos customer service.

US: techsupport@thamesandkosmos.com
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# What's inside your experiment kit:



# Checklist: Find – Inspect – Check off

~	No.	Description	Qty.	Item No.
O	1	Joint pin	18	1156-W10-A1R
O	2	Shaft plug	8	7026-W10-H1R
O	3	Shaft pin	9	7026-W10-J3R
O	4	3-hole rod	1	7026-W10-Q1W
O	5	3-hole cross rod	5	7026-W10-X1W
O	6	3-hole dual rod	2	7061-W10-R1W
O	7	3-hole wide rounded rod, white	2	7404-W10-C1W
O	8	3-hole wide rounded rod, gray	6	7404-W10-C1S
O	9	5-hole rod, white	1	7413-W10-K2W
O	10	5-hole rod, gray	4	7413-W10-K2S1
O	11	5-hole cross rod, white	2	7413-W10-K3W
O	12	5-hole cross rod, black	2	7413-W10-K3D
O	13	5-hole dual rod B, gray	6	7026-W10-S2S1
0	14	5-hole dual rod C, white	2	7026-W10-S3W
0	15	5-hole dual rod C, gray	2	7026-W10-S3S2
O	16	7-hole wide rounded rod, white	2	7404-W10-C2W
O	17	7-hole wide rounded rod, gray	6	7404-W10-C2S
O	18	7-hole flat rounded rod, gray	3	7404-W10-C3S
O	19	11-hole rod, white	2	7026-W10-C1W
O	20	Square frame B	2	7026-W10-T2W
O	21	Square frame A	1	7026-W10-V1W
O	22	Short frame, white	2	7413-W10-I1W
O	23	14-hole dual rod, gray	2	7413-W10-H1S1
O	24	Motor shaft	4	7026-W10-L1W
O	25	3-cm axle	1	7413-W10-N1D
O	26	10-cm axle	1	7413-W10-L2D
O	27	90-degree converter X, white	4	7061-W10-J1W
O	28	90-degree converter Y, white	4	7061-W10-J2W

	No.	Description	Qty.	Item No.
O	29	90-degree converter Y, gray	6	7061-W10-J2S2
0	30	Small gear	8	7026-W10-D2S
O	31	Worm	1	7344-W10-A1W
0	32	Crank bar	1	7026-W10-J2D
O	33	O-ring	2	R12-08S
O	34	Small pulley	2	7344-W10-N3S
<u>O</u>	35	Body plate 3	3	7392-W10-L1TD
O	36	Body plate 4	3	7392-W10-L2TD
0	37	Leg left	1	7397-W10-C1W
0	38	Leg right	1	7397-W10-C2W
0	39	Diagonal connector	6	7404-W10-B2S
O	40	30-mm tube	4	7400-W10-G1D
O	41	20-mm tube	1	7400-W10-G2D
0	42	Short anchor pin	6	880-W10-M1B
O	43	Anchor pin	51	7061-W10-C1R
<u>O</u>	44	Two-to-one converter	4	7061-W10-G1W
0	45	Button pin	4	7061-W10-E1D
<u>O</u>	46	Anchor pin lever	1	7061-W10-B1Y
<u>O</u>	47	Motor unit 1	1	7392-W85-B1
<u>O</u>	48	Medium gear	10	7346-W10-C1S
0	49	Motor unit 2	1	7400-W85-A
0	50	6.5-cm axle	3	7416-W10-C1D
0	51	Jaw, upper	1	7416-W10-A1W
O	52	Jaw, lower	1	7416-W10-A2W
O	53	Bluetooth battery box	1	7416-W85-A
O	54	Ultrasonic sensor	1	7416-W85-B
O	55	Flexible shaft	2	7416-W85-C

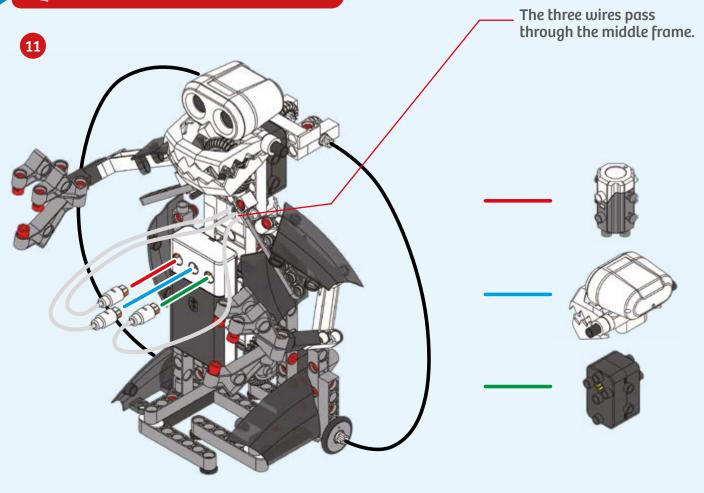
Android (see page 7 for hardware requirements)

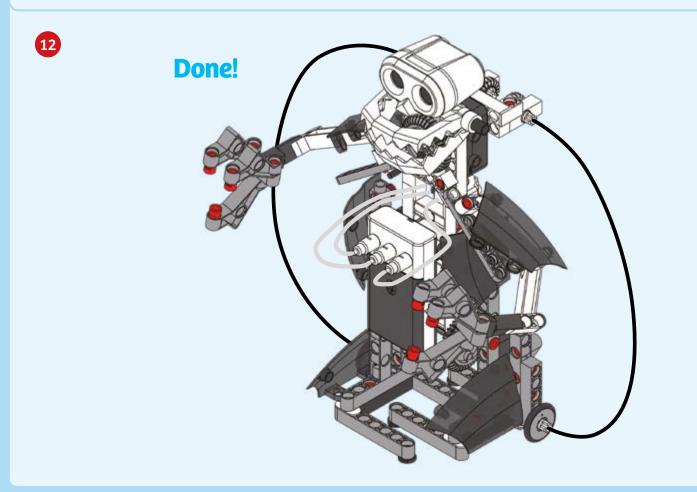
# >>> TABLE OF CONTENTS



Safety Information	. Inside front cover
Kit Contents	1
Tips and Tricks	2
Table of Contents	3
Robots: Sensing, Thinking Machines	
Getting Started	4
About Ultrasound	
Downloading and Using the App	6
Writing Programs	7
The models:	
Bipedal Droid	13
Programming the Bipedal Droid	17
Spy Bot	18
Using the Spy Bot	23
Beetle	
Programming the Beetle	31
Crocodile	
Programming the Crocodile	38
Tiltrotor Aircraft	
Programming the Tiltrotor Aircraft	49
Robo Dog	
Programming the Robo Dog	55
Robotosaurus	
Programming the Robotosaurus	61
Catapult	
Programming the Catapult	64
Publisher's information	





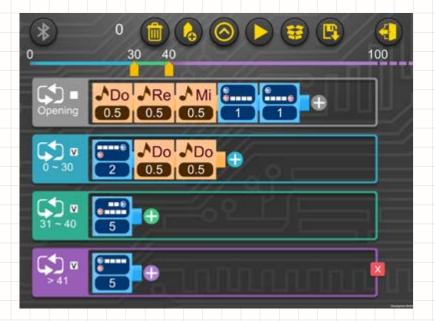




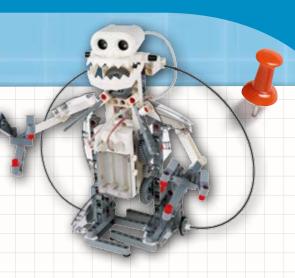
#### SAMPLE PROGRAM FOR THE BIPEDAL DROID

Use this program to make your bipedal droid walk forward until it detects an obstacle with the ultrasound sensor. When the obstacle is detected, the robot will turn to the side. When the robot no longer detects an obstacle, it will walk forward again.

This program is preloaded in the app under Program 7. Test it out and write down how the robot behaves for each program segment below.



## **PROGRAMMING NOTES**



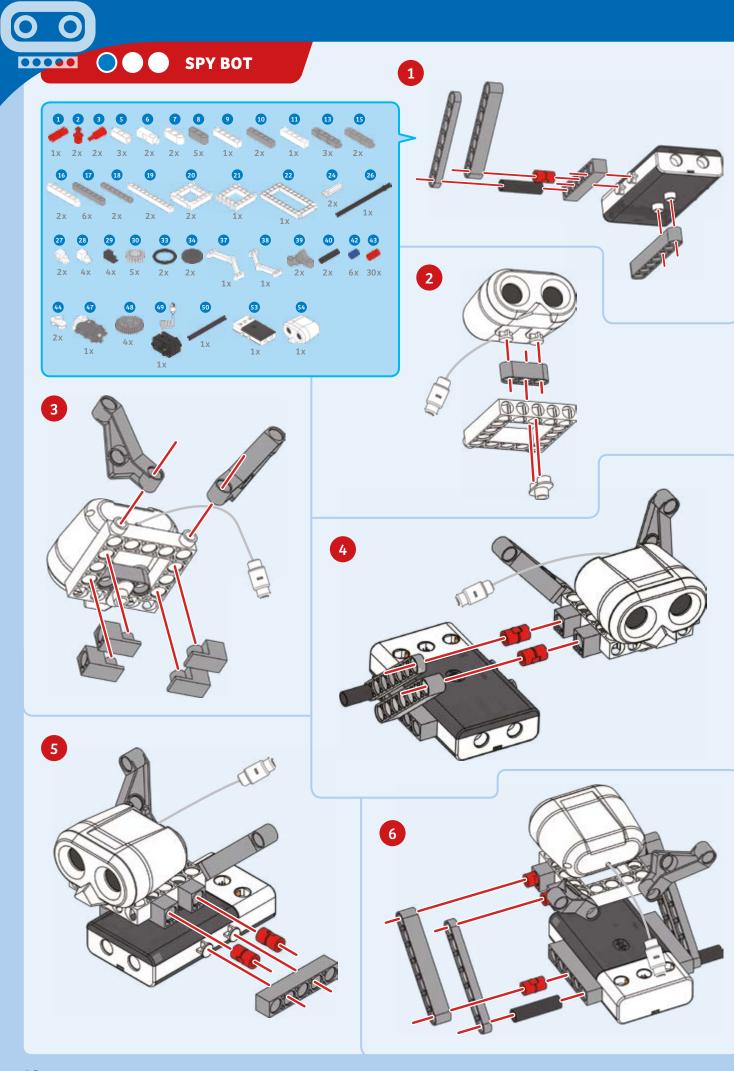
DEMO PROGRAM:
Program 7
Program 7

# **OPENING SEGMENT:**

#### **SEGMENT 0-30:**

### **SEGMENT 31-40:**

## SEGMENT >41:





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